

About the holonomy and curvature of Finsler manifolds

joint work with P.T. Nagy

March 25, 2015, Debrecen

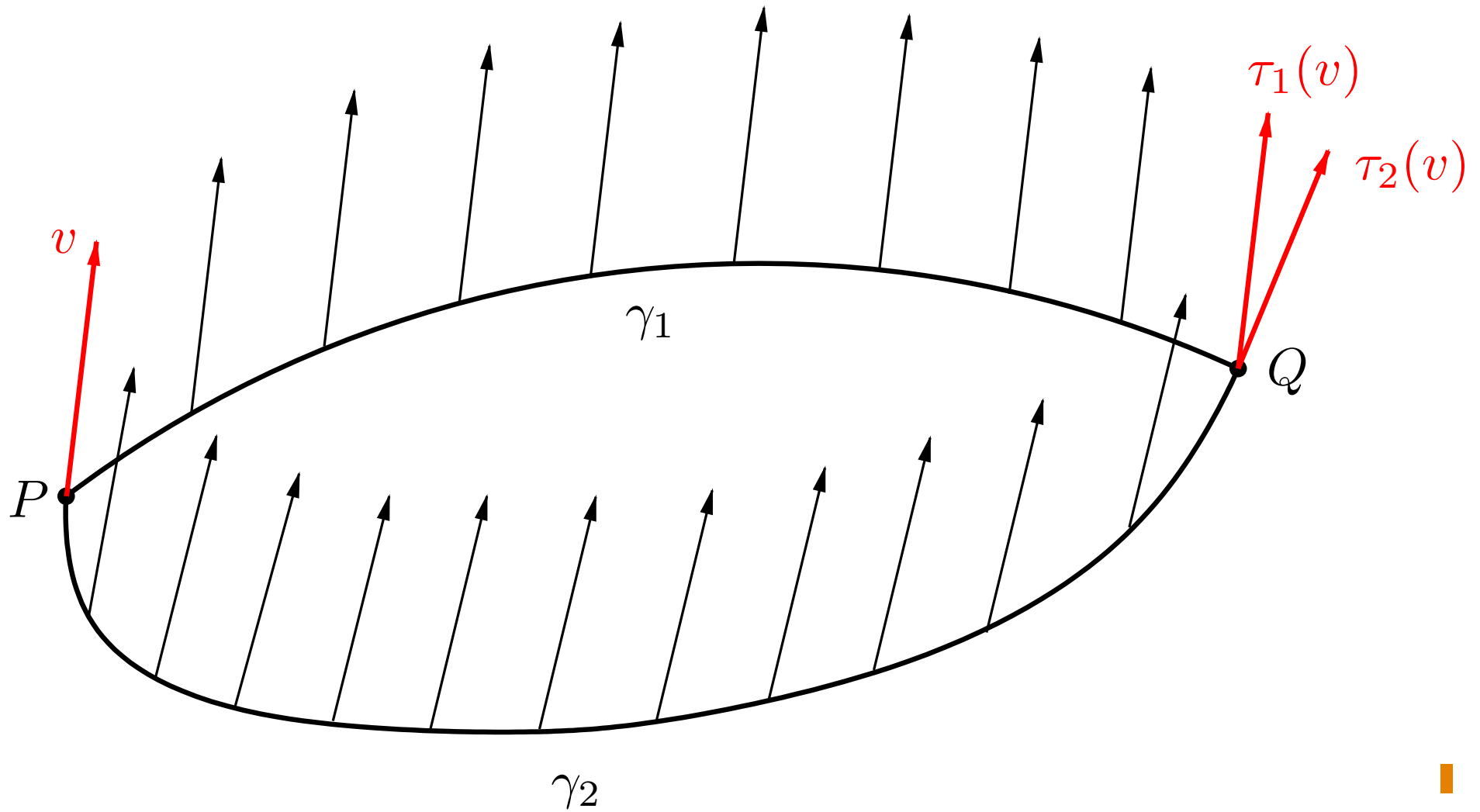
Abstract



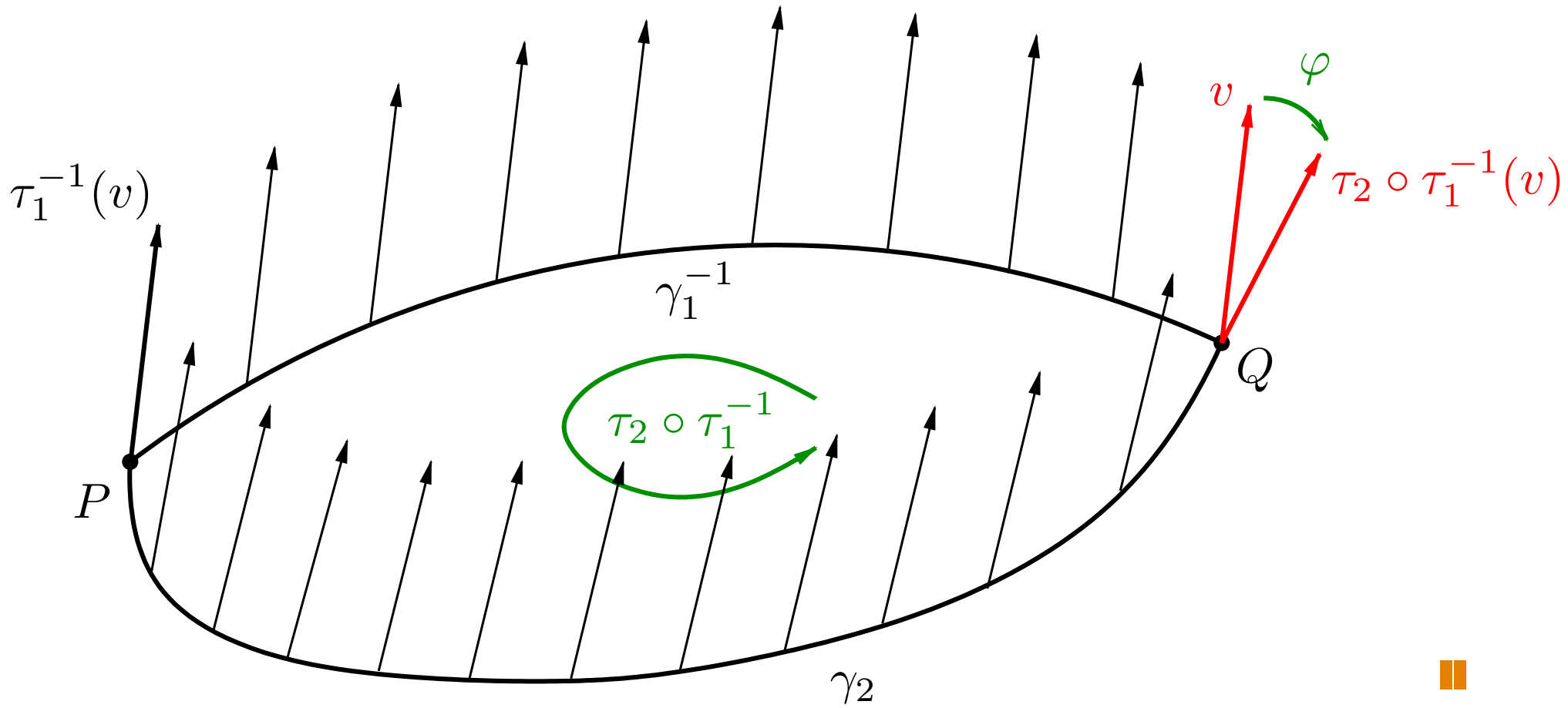
The aim of this talk is to present some new results about the holonomy of the Finsler manifolds ■

- Finsler manifolds, ■
- Holonomy group, ■
- Tangent Lie algebras to the holonomy group, ■
- The **curvature algebra** and **infinitesimal holonomy algebra**, ■
- New results about the holonomy of the Finsler manifolds. ■

Parallel translation along curves

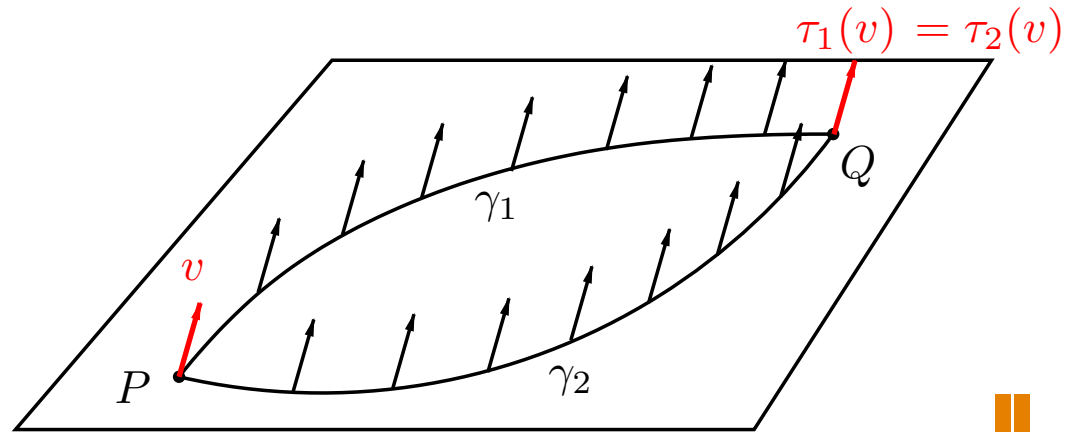


Holonomy

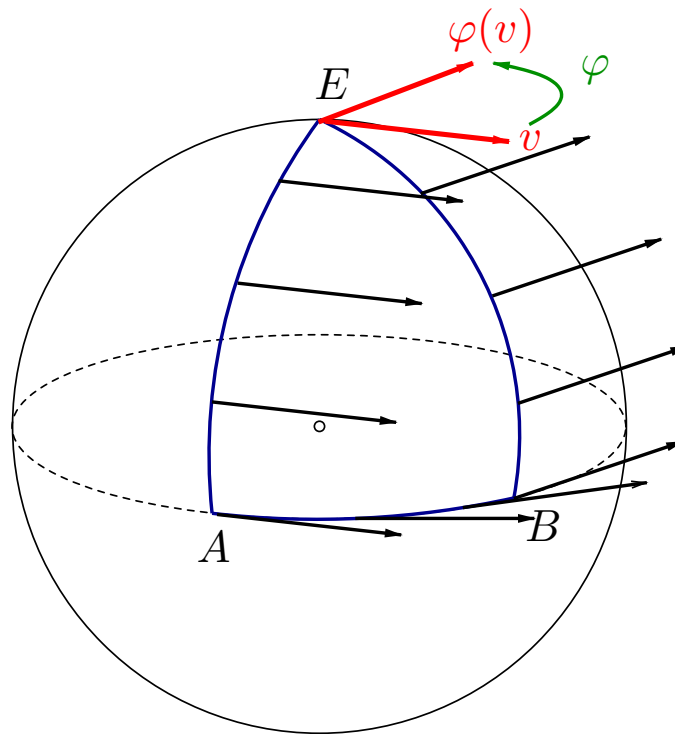


Examples

1. Plane: $\mathbf{R} \equiv \mathbf{0}$



2. Sphere: $\mathbf{R} \neq \mathbf{0}$



Parallel translation, holonomy

- Riemannian manifolds: $\langle \cdot, \cdot \rangle_{\mathbf{p}} = g_{ij}(\mathbf{x}) dx^i \otimes dx^j$

- Finslerian manifolds: $\langle \cdot, \cdot \rangle_{(\mathbf{p}, \mathbf{v})} = g_{ij}(\mathbf{x}, \mathbf{y}) dx^i \otimes dx^j$

- Geodesics: $\ddot{x}^i + 2G^i(x, \dot{x}) = 0,$

$$G^i(x, y) := \frac{1}{4} g^{il}(x, y) \left(2 \frac{\partial g_{jl}}{\partial x^k}(x, y) - \frac{\partial g_{jk}}{\partial x^l}(x, y) \right) y^j y^k.$$

- Parallel vector field $X(t)$ along a curve $c(t)$:

$$\nabla_{\dot{c}} X(t) = \left(\frac{dX^i(t)}{dt} + \Gamma_j^i(c(t), X(t)) \dot{c}^j(t) \right) \frac{\partial}{\partial x^i} = 0, \quad \Gamma_j^i = \frac{\partial G^i}{\partial y^j}.$$

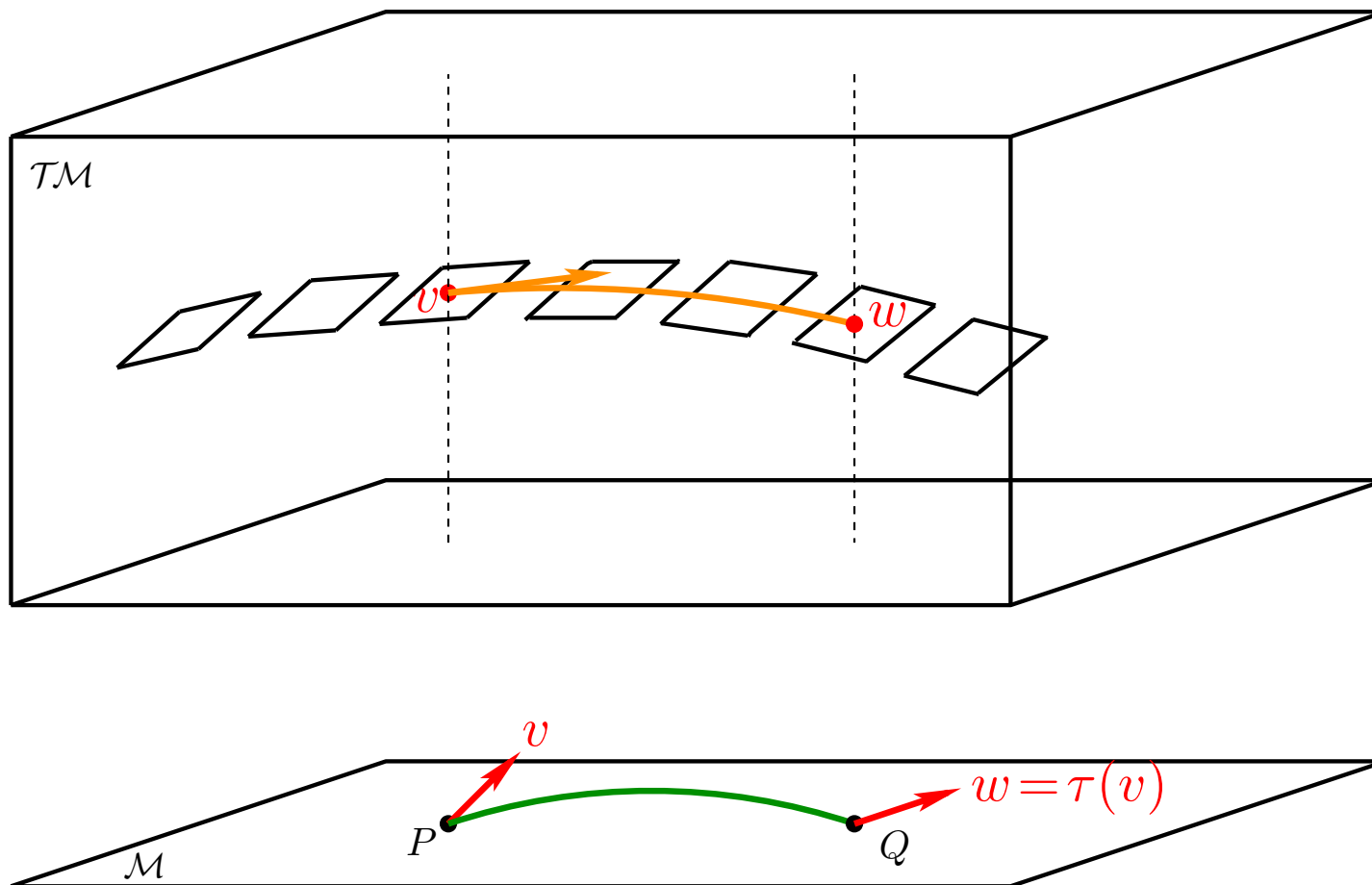
- Parallel translation along a curve $c: [0, 1] \rightarrow M$:

$$\tau_c: T_{c_0}M \rightarrow T_{c_1}M, \quad X_0 \Rightarrow X(t) \Rightarrow \tau X_0 = X(1) \Rightarrow \tau_c: \mathcal{I}_{c_0} \rightarrow \mathcal{I}_{c_1}$$

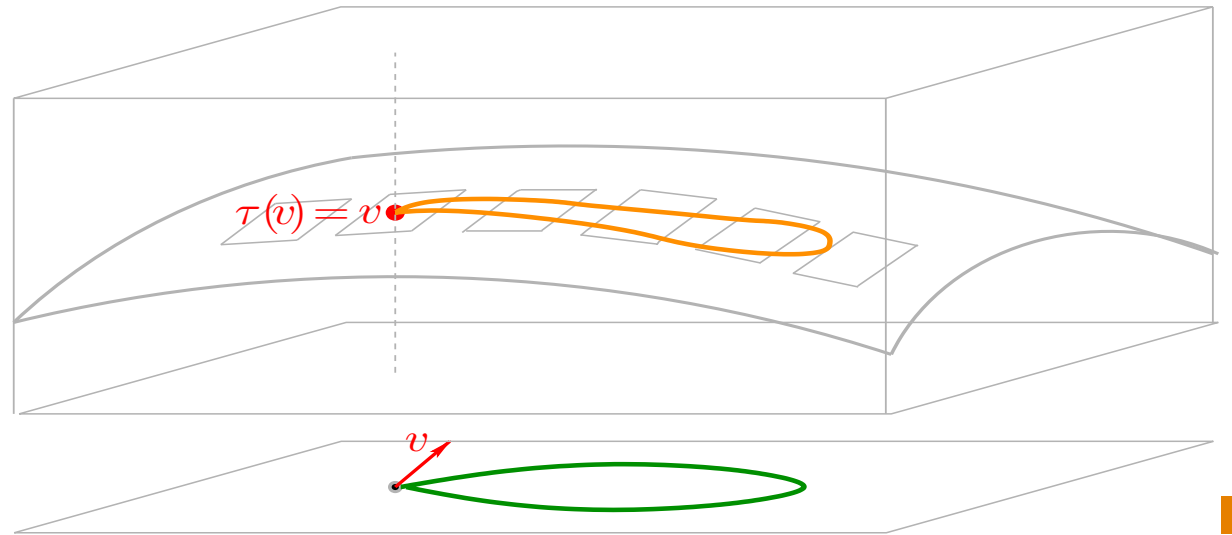
- The *holonomy group* is generated by parallel translation along closed curves

\Rightarrow subgroup of $\text{Diff}^\infty(\mathcal{I}_x)$ determined by parallel translations.

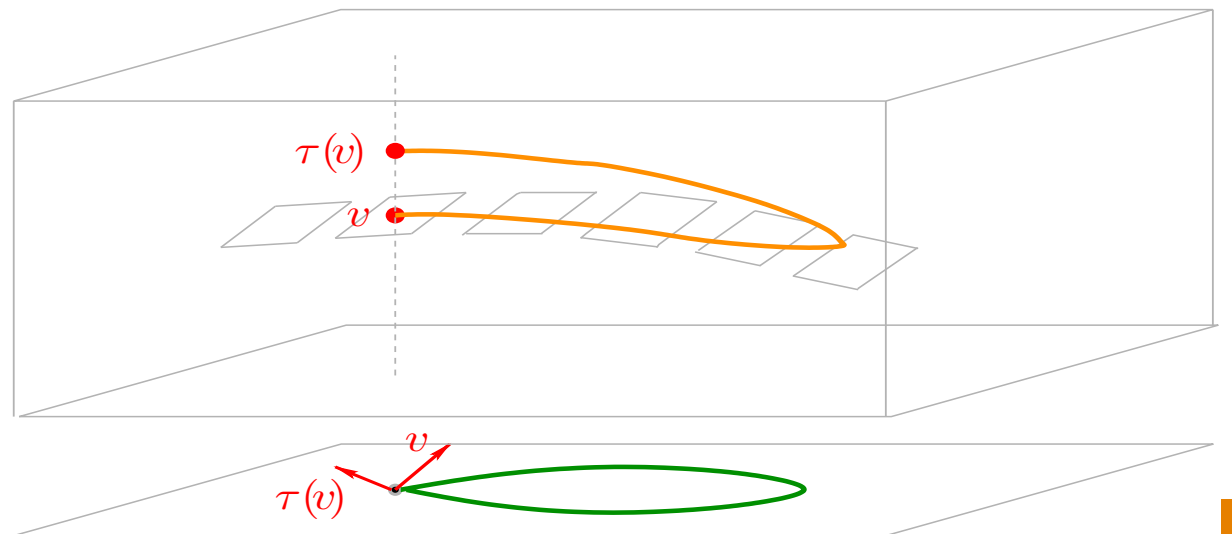
Parallel translation: geometric construction



- $R \equiv 0$ ■



- $R \neq 0$ ■



Tangent Lie algebras to a subgroup H of $\text{Diff}^\infty(\mathcal{I})$

Def: • A vector field X is called *tangent* to $H \subset \text{Diff}^\infty(\mathcal{I})$, if there exists $\{\phi_t\}$ in H such that

$$\phi_0 = \text{Id}, \quad \left. \frac{\partial \phi_t}{\partial t} \right|_{t=0} = X.$$

- A Lie algebra \mathfrak{h} is *tangent* to H , if its elements are tangent to H .

\mathfrak{h} tangent to $H \quad \Rightarrow \quad$ information on H
--

Prop: If \mathfrak{h} is tangent to a closed subgroup H of $\text{Diff}^\infty(\mathcal{I})$, then $\exp(\mathfrak{h}) \subset H$.

Proof: • $X \in \mathfrak{h}$, the 1-parameter family of diffeomorphisms $\{\phi(t) \in H\}_{t \in \mathbb{R}}$:

$$\left\{ \left(\phi \left(\frac{t}{n} \right) \right)^n \in H \right\}_{t \in \mathbb{R}} \longrightarrow \{\exp tX\}_{t \in \mathbb{R}}$$

- H is closed $\Rightarrow \{\exp tX\}_{t \in \mathbb{R}} \subset H$.

Definition: A vector field X is *strongly tangent* to a subgroup H , if there exists a $k \in \mathbb{N}$ and a smooth k -parameter family $\{\phi_{(t_1, \dots, t_k)}\}$ of diffeomorphisms in H such that

1. $\phi_{(t_1, \dots, t_k)} = \text{Id}$, if $t_j = 0$ for some $1 \leq j \leq k$;

2. $\left. \frac{\partial^k \phi_{(t_1, \dots, t_k)}}{\partial t_1 \dots \partial t_k} \right|_{(t_1, \dots, t_k) = (0, \dots, 0)} = X$.

Remark: If X is strongly tangent to H , then it is also tangent to H .

Proposition: The Lie algebra generated by strongly tangent vector fields is tangent to H .

$$\begin{aligned} X_1 \text{ strongly tangent} &\Rightarrow \{\phi_{(t_1, \dots, t_{k_1})}^1\} \\ X_2 \text{ strongly tangent} &\Rightarrow \{\phi_{(s_1, \dots, s_{k_2})}^2\} \end{aligned} \Rightarrow [\phi_{(t_1, \dots, t_{k_1})}^1, \phi_{(s_1, \dots, s_{k_2})}^2]$$

$$[\phi_{(t_1, \dots, t_{k_1})}^1, \phi_{(s_1, \dots, s_{k_2})}^2] \Rightarrow [X_1, X_2]$$

Curvature algebra and infinitesimal holonomy algebra ■

- $\mathfrak{R}(M)$: the *curvature algebra* is the smallest Lie algebra generated by curvature vector fields. ■
- $\mathfrak{hol}^*(M)$: the *infinitesimal holonomy algebra* is the smallest Lie algebra generated by curvature vector fields and by horizontal Berwald differentiation. ■

Proposition: $\mathfrak{R}_x(M)$ and $\mathfrak{hol}_x^*(M)$ are tangent to $\text{Hol}_x(M)$. ■

Holonomy of Finsler surfaces $(\dim M = 2)$

Remarks: • $\mathcal{I}_x \simeq \mathbb{S}^1$,

- $\text{Hol}_x(M) \subset \text{Diff}_+^\infty(\mathbb{S}^1)$
- $\dim \mathfrak{K}_x(M) \leq 1$,
- $\mathfrak{hol}_x^*(M)$ can be higher (even infinite) dimensional.

Proposition: *If $\mathfrak{hol}_x^*(M)$ contains 4 simultaneously non-vanishing \mathbb{R} -linearly independent vector fields, then $\text{Hol}_x(M)$ is not a finite-dimensional Lie group.*

Proof. S. Lie: If a finite-dimensional connected Lie group acts on a 1-dimensional manifold without fixed points, then its dimension is less than 4.

Some results: Finsler surfaces of non zero constant flag curvature

1. Tensorial characterization of the cases, when $\mathfrak{hol}^*(x) = \mathfrak{K}_x$,
2. Examples where $\mathfrak{hol}^*(x) = \mathfrak{K}_x$,
3. Examples where $\dim(\mathfrak{hol}^*(x)) = \infty$.

Finsler 2-manifolds with maximal holonomy group

Projectively flat Finsler spaces of constant curvature: $G^i(x, y) = \mathcal{P}(x, y)y^i$

Thm. If there exists $x_0 \in M$, where $\mathcal{F}(x_0, y) = \|y\|$ and $\mathcal{P}(x_0, y) = c \cdot \|y\|$, then

$$\overline{\text{Hol}_{x_0}(M)} = \text{Diff}_+^\infty(\mathbb{S}^1).$$

- $\mathcal{I}_{x_0} = \mathbb{S}^1$, $\text{Hol}_0(M) \subset \text{Diff}_+^\infty(\mathbb{S}^1)$
- $\text{hol}_0^*(M) \supset \mathbf{F}(\mathbb{S}^1) = \left\{ \cos nt \frac{\partial}{\partial t}, \sin nt \frac{\partial}{\partial t} \right\}_{n \in \mathbb{N}} \Rightarrow \overline{\mathbf{F}(\mathbb{S}^1)} = \overline{\text{hol}_0^*(M)} = \mathfrak{X}(\mathbb{S}^1)$
- $\exp(\mathfrak{X}(\mathbb{S}^1)) \subset \overline{\exp(\text{hol}_0^*(M))} \subset \text{Diff}_+^\infty(\mathbb{S}^1)$
- $\langle \exp(\mathfrak{X}(\mathbb{S}^1)) \rangle \subset \overline{\langle \exp(\text{hol}_0^*(M)) \rangle} \subset \overline{\text{Hol}_0(M)} \subset \text{Diff}_+^\infty(\mathbb{S}^1)$
- $\langle \exp(\mathfrak{X}(\mathbb{S}^1)) \rangle$ conj. inv. \Rightarrow normal subgroup in $\text{Diff}_+^\infty(\mathbb{S}^1)$
- $\text{Diff}_+^\infty(\mathbb{S}^1)$ simple $\Rightarrow \langle \exp(\mathfrak{X}(\mathbb{S}^1)) \rangle = \text{Diff}_+^\infty(\mathbb{S}^1) \Rightarrow \overline{\text{Hol}_0(M)} = \text{Diff}_+^\infty(\mathbb{S}^1)$

Corollary: The holonomy group of the Funk metric (constant negative curvature) and of the Bryant-Shen 2-spheres (constant positive curvature) are maximal.

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Acknowledgements: The research by the authors leading to these results was funded in part by the European Union's Seventh Framework Programme (FP7/2007-2013) under grant agreement no. 318202.